## Generative Models

An Introduction to Variational Autoencoders and their Extensions

#### Outline

- Introduction to generative models
- Variational autoencoder
- Supervised (conditional) variational autoencoder
- Semi-supervised variational autoencoder

## Introduction to generative models

# Probabilistic models Setup

- In ML, we assume datapoints  $\boldsymbol{x}$  and labels  $\boldsymbol{y}$  are generated from an underlying true probabilistic model
- goal is to build probabilistic model that is close to the true model
- Joint distribution p(x, y) = p(x)p(y | x)

### Discriminative vs generative models

- Two types of probabilistic models
- Discriminative models model p(y | x) directly, ignore p(x)
  - logistic regression, SVMs, kNN, random forests, some neural nets
- Generative models model p(x) (p(x, y) for supervised learning)
  - Naive Bayes, Hidden Markov Models, Variational Autoencoders

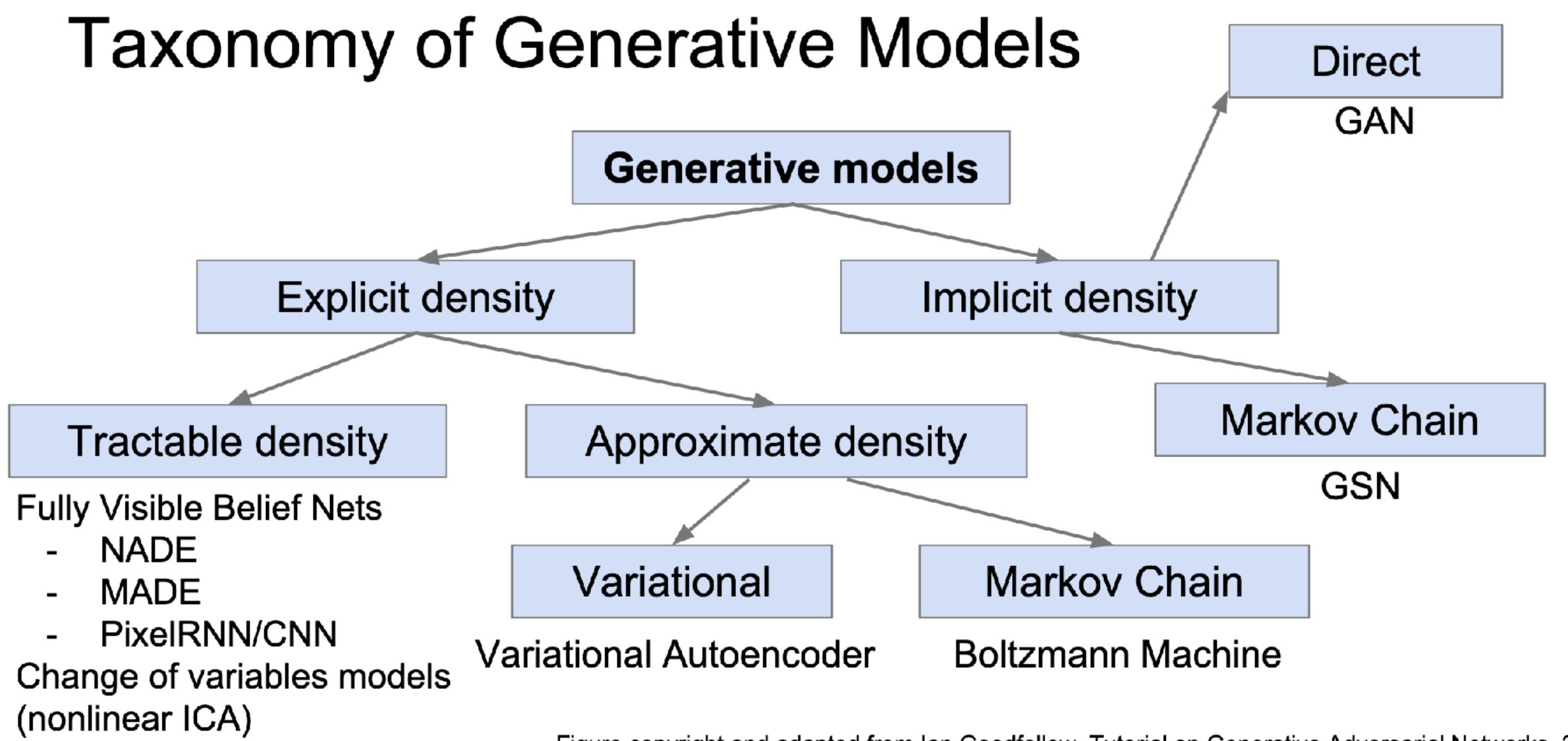
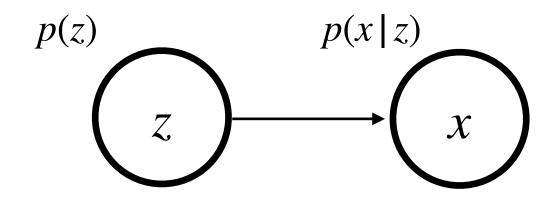


Figure copyright and adapted from Ian Goodfellow, Tutorial on Generative Adversarial Networks, 2017.

• Unsupervised latent variable model - hidden variable z, datapoint x



- Example: x is an image of a face, z represents facial features
- Choose p(z) to be any simple distribution e.g.  $\mathcal{N}(\mathbf{0}, \mathbf{I})$
- Model  $p(x \mid z)$  using neural network with parameters  $\theta \to p_{\theta}(x \mid z)$
- Posterior p(z | x) could also be of interest

#### What is the problem?

• 
$$p(x) = \int p_{\theta}(x \mid z)p(z)dz$$
 -> intractable

- Turns out posterior is also intractable:  $p(z \mid x) = \frac{p_{\theta}(x \mid z)p(z)}{p(x)}$
- We can't even compute p(x)
  - How can we train a model?
  - How can we compute p(z | x)?

# Variational Autoencoder (VAE) Solution

- Kill two birds with one stone train model and get approximation to  $p(z \mid x)$
- Can use Markov Chain Monte Carlo (MCMC) or Variational Inference (VI)

# Variational Autoencoder (VAE) MCMC or VI?

- MCMC estimates gradient of p(x) via samples from  $p(z \mid x)$ 
  - expensive, unfeasible for large datasets
- VI assumes functional form for  $p(z \mid x) \rightarrow q(z \mid x)$ 
  - Approximate but efficient, scales well to large datasets
- VAEs use VI (hence the name 'variational')

# Variational Autoencoder (VAE) Using VI to solve our problem

- Parameterise  $q(z \mid x)$  using a neural network with parameters  $\phi \to q_{\phi}(z \mid x)$
- VAE with encoder  $q_{\phi}(z \mid x)$ , decoder  $p_{\theta}(x \mid z)$
- Still need a way to train the model derivation follows

#### Deriving the training objective

Marginalisation

Definition of expectation

$$p(x) = \int p(x|z)p(z)dz$$

$$= \int p(x|z)\frac{p(z)}{q(z|x)}q(z|x)dz$$

$$= \mathbb{E}_{z \sim q(z|x)}\left(p(x|z)\frac{p(z)}{q(z|x)}\right)$$

$$\log p(x) = \log\left[\mathbb{E}_{z \sim q(z|x)}\left(p(x|z)\frac{p(z)}{q(z|x)}\right)\right]$$

#### Deriving the training objective

$$\log p(x) = \log \left[ \mathbb{E}_{z \sim q(z|x)} \left( p(x|z) \frac{p(z)}{q(z|x)} \right) \right]$$

Jensen's inequality

$$\log p(x) \ge \mathbb{E}_{z \sim q(z|x)} \log \left[ p(x|z) \frac{p(z)}{q(z|x)} \right]$$

Definition

$$\log p(x) \ge \mathbb{E}_{z \sim q(z|x)} \left[ \log p(x|z) + \log p(z) - \log q(z|x) \right]$$

$$\mathsf{ELBO} = \mathbb{E}_{z \sim q(z|x)} \left[ \log p(x|z) + \log p(z) - \log q(z|x) \right]$$

Form usually used in VAEs

$$\mathsf{ELBO} = \mathbb{E}_{z \sim q(z|x)} \log p(x|z) - D_{KL} \left( q(z|x) \mid |p(z) \right)$$

Reconstruction term

KL term

#### Training objective

$$\underset{\theta,\phi}{\operatorname{arg\,max}} \ \mathsf{ELBO} = \underset{\theta,\phi}{\operatorname{arg\,max}} \ \left[ \mathbb{E}_{z \sim q_{\phi}(z|x)} \log p_{\theta}(x\,|\,z) - D_{\mathit{KL}} \left( \log q_{\phi}(z\,|\,x) \,|\,|\,p(z) \right) \right]$$

• To train, maximise ELBO instead of log p(x)

#### Maximising ELBO gives good posterior

- Can show that:
  - ELBO =  $\log p(x) D_{KL} \left( q_{\phi}(z | x) | | p(z | x) \right)$
  - KL term always nonnegative missing term in the lower bound equation

$$\begin{aligned} \arg\max_{\phi} \; \mathsf{ELBO} &= \arg\max_{\phi} \left[ \log p(x) - D_{KL} \left( q_{\phi}(z \mid x) \, || \, p(z \mid x) \right) \right] \\ &= -\arg\max_{\phi} \; D_{KL} \left( q_{\phi}(z \mid x) \, || \, p(z \mid x) \right) \\ &= \arg\min_{\phi} \; D_{KL} \left( q_{\phi}(z \mid x) \, || \, p(z \mid x) \right) \end{aligned}$$

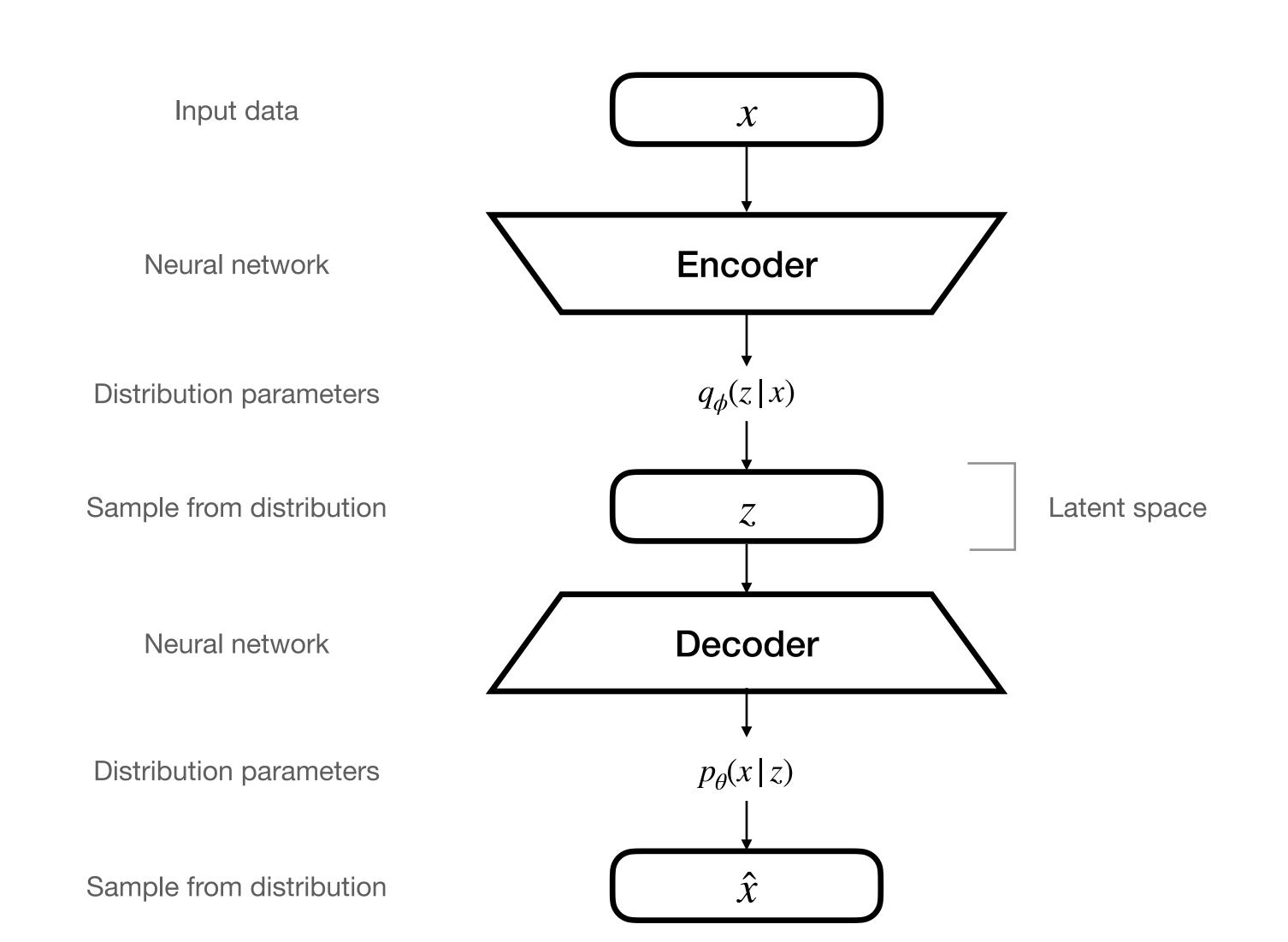
-> Maximising ELBO minimises KL divergence between true posterior and approximate posterior

#### Training procedure

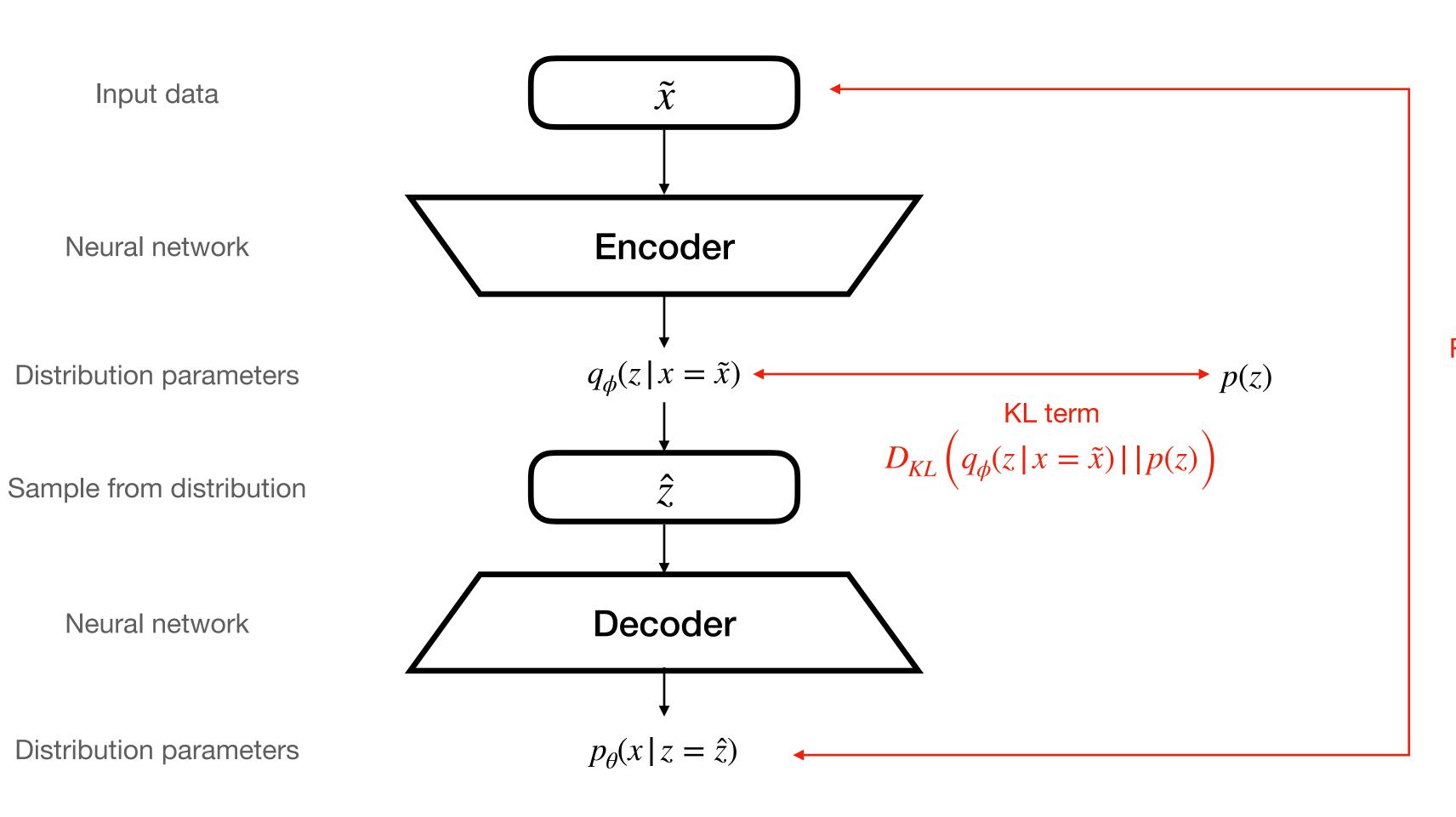
$$\mathsf{ELBO} = \mathbb{E}_{z \sim q_{\phi}(z|x)} \log p_{\theta}(x|z) - D_{KL} \left( q_{\phi}(z|x) \mid |p(z)| \right)$$

- Sample z from  $q_{\phi}(z \mid x)$  using datapoint x
- Compute  $p_{\theta}(x \mid z)$
- Compute KL term analytically or via Simple Monte Carlo

What does this have to do with autoencoders?

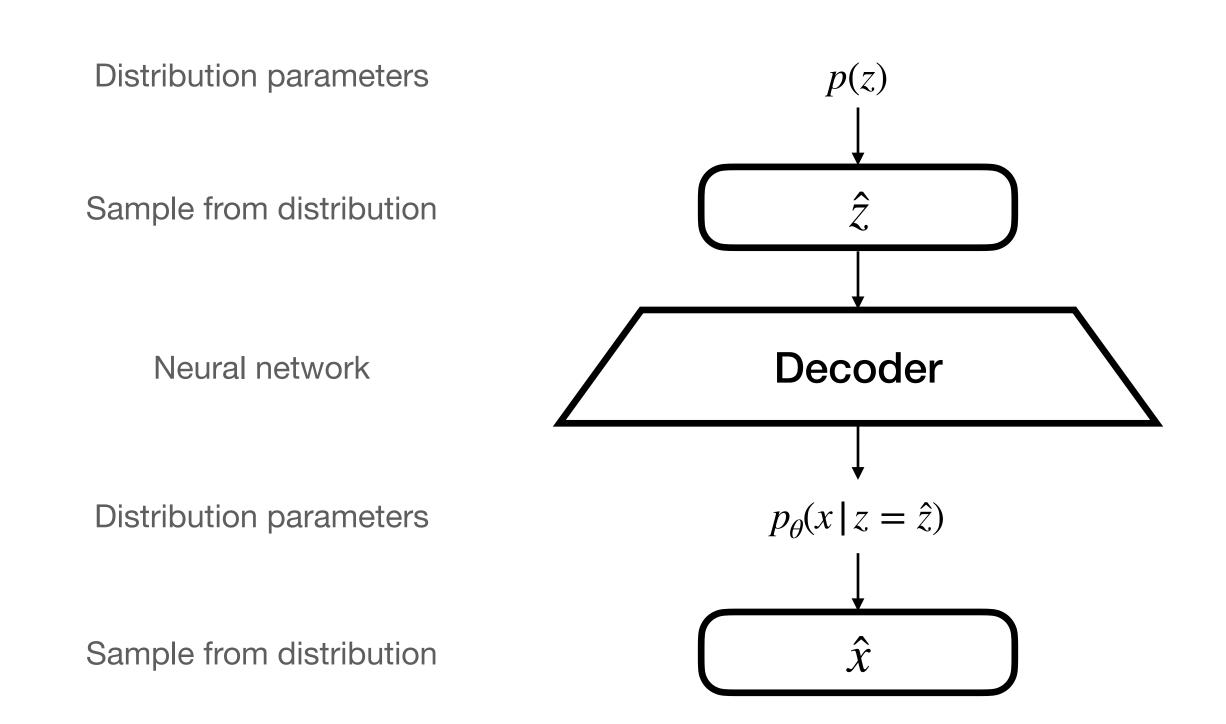


#### What does training look like?



Reconstruction term  $p_{\theta}(x = \tilde{x} | z = \hat{z})$ 

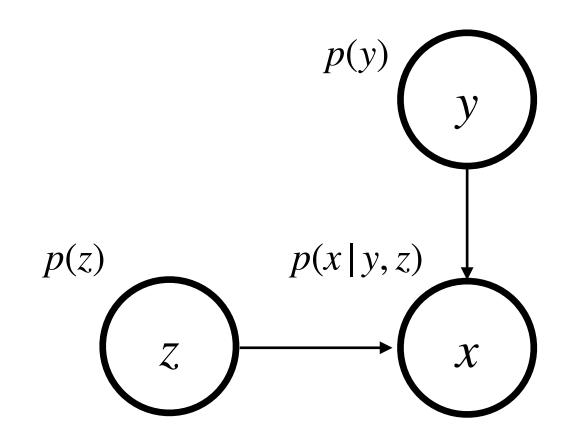
What does the autoencoder look like at generation time?



## Conditional VAE (Supervised VAE)

What is a conditional (supervised) VAE?

- Extension of VAE to supervised setting
- Each datapoint x generated from latent variable z and label  $y \rightarrow p(x \mid y, z)$
- Goal: build generative model p(x, y)

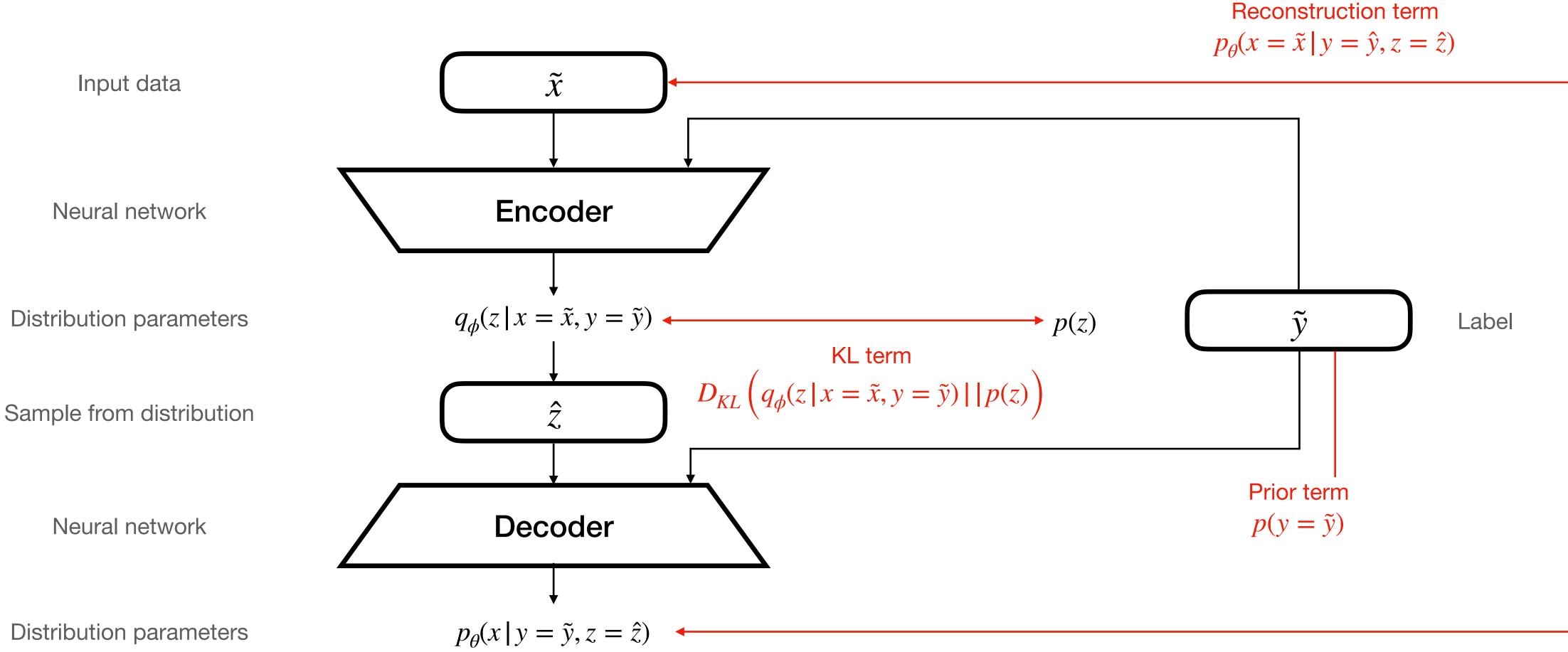


#### What does the training objective look like?

Condition data generation on y

$$\log p(x) \geq \mathsf{ELBO}(x)$$
 
$$\log p(x) \geq \mathbb{E}_{z \sim q(z|x)} \left[ \log p(x|z) + \log p(z) - \log q(z|x) \right]$$
 
$$\log p(x,y) \geq \mathbb{E}_{z \sim q(z|x,y)} \left[ \log p(x|y,z) + \log p(y,z) - \log q(z|x,y) \right]$$
 
$$\log p(x,y) \geq \mathbb{E}_{z \sim q(z|x,y)} \left[ \log p(x|y,z) + \log p(y) + \log p(z) - \log q(z|x,y) \right]$$
 
$$\log p(x,y) \geq \mathbb{E}_{z \sim q(z|x,y)} \left[ \log p(x|y,z) + \log p(y) + \log p(z) - \log q(z|x,y) \right]$$
 
$$\log p(x,y) \geq \mathbb{E}_{z \sim q(z|x,y)} \left[ \log p(x|y,z) \right] + \log p(y) + D_{KL} \left( q(z|x,y) | | p(z) \right)$$
 
$$\log p(x,y) \geq \mathsf{ELBO}(x,y)$$

#### What does training look like?



Neural network

Input data

Distribution parameters

What does generation look like?

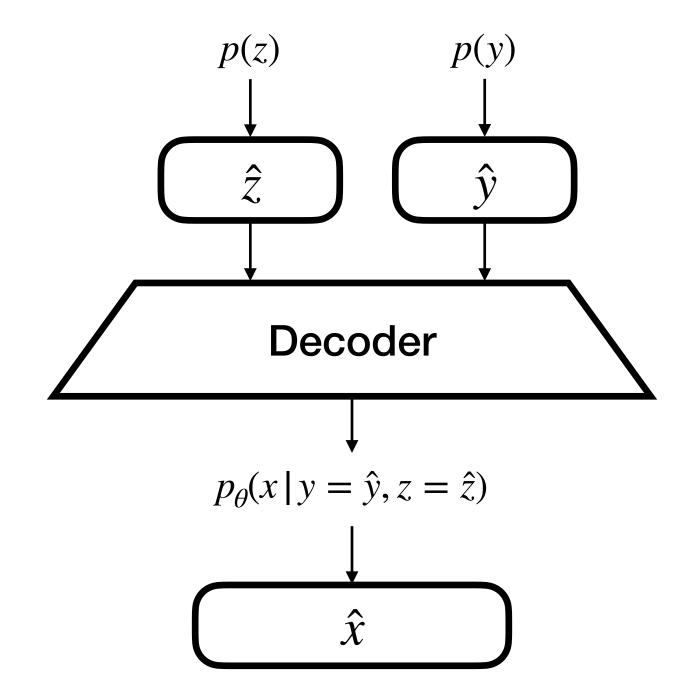


Sample from distribution

Neural network

Distribution parameters

Sample from distribution

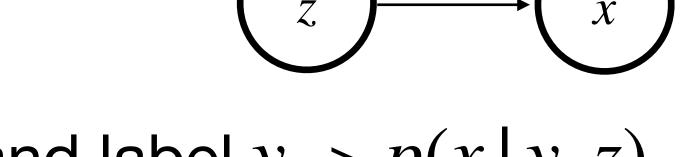


#### What is semi-supervision?

- Supervised learning each data point has a label
- Unsupervised learning no data points have labels
- Semi-supervised learning small number of data points have labels

#### What is a semi-supervised VAE?

- Extension of VAE to semi-supervised setting
- For datapoints with labels:



p(z)

p(x | y, z)

- Each datapoint x generated from latent variable z and label  $y \rightarrow p(x \mid y, z)$
- For datapoints without labels:
  - Each datapoint x generated from latent variables z and  $y \rightarrow p(x \mid y, z)$

#### What does the training objective look like?

For data points with labels

$$\log p(x,y) \ge \mathbb{E}_{z \sim q(z|x,y)} \left[ \log p(x|y,z) \right] + \log p(y) + D_{KL} \left( q(z|x,y) \mid |p(z)| \right) = -\mathcal{L}(x,y)$$

For data points without labels

$$\log p(x) \geq \mathbb{E}_{y,z \sim q(y,z|x)} \left[ \log p(x \mid y,z) + \log p(y) + \log p(z) - \log q(y,z \mid x) \right]$$

$$\log p(x) \geq \mathbb{E}_{y,z \sim q(y,z|x)} \left[ \log p(x \mid y,z) + \log p(y) + \log p(z) - \log q(y \mid x) - \log q(z \mid x,y) \right]$$

$$\log p(x) \geq \mathbb{E}_{y,z \sim q(y,z|x)} \left[ \log p(x \mid y,z) + \mathbb{E}_{y \sim q(y|x)} \left[ \log p(y) - \log q(y \mid x) \right] + \mathbb{E}_{y \sim q(y|x), z \sim q(z|x,y)} \left[ \log p(z) - \log q(z \mid x,y) \right]$$

$$\log p(x) \geq \mathbb{E}_{y \sim q(y|x), z \sim q(z|x,y)} \left[ \log p(x \mid y,z) \right] - D_{KL} \left( q(y \mid x) \mid |p(y) \right) + \mathbb{E}_{y \sim q(y|x)} \left[ D_{KL} \left( q(z \mid x,y) \mid |p(z) \right) \right] = -\mathcal{U}(x)$$

#### From training objective parts to model

For data points with labels

$$\log p(x,y) \ge \mathbb{E}_{z \sim q(z|x,y)} \left[ \log p(x|y,z) \right] + \log p(y) + D_{KL} \left( q(z|x,y) \mid |p(z)| \right) = -\mathcal{L}(x,y)$$

For data points without labels

$$\log p(x,y) \ge \mathbb{E}_{y \sim q(y|x), z \sim q(z|x,y)} \left[ \log p(x|y,z) \right] - D_{KL} \left( q(y|x) | |p(y) \right) + \mathbb{E}_{y \sim q(y|x)} \left[ D_{KL} \left( q(z|x,y) | |p(z) \right) \right] = -\mathcal{U}(x)$$

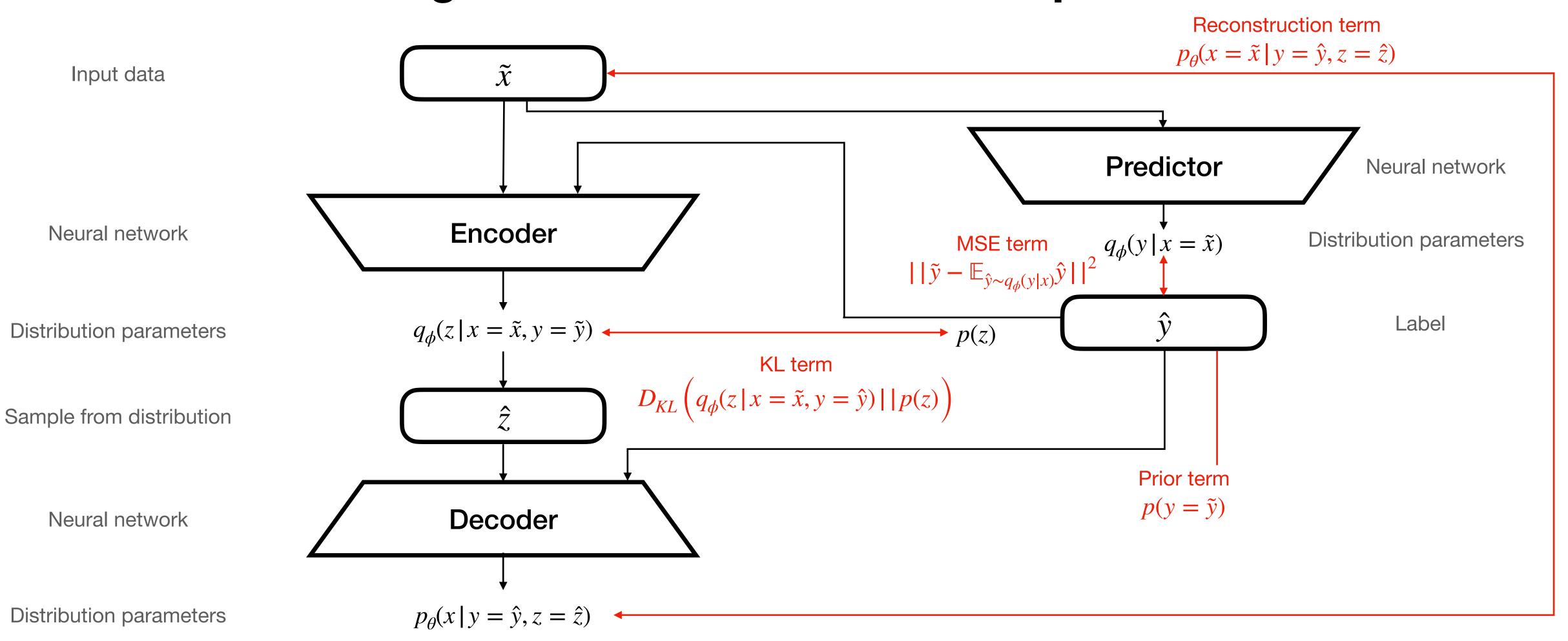
- $p_{\theta}(x \mid y, z)$ : decoder
- $q_{\phi}(z | x, y)$  : encoder
- $q_{\phi}(y \mid x)$ : 'predictor'

#### Overall training objective

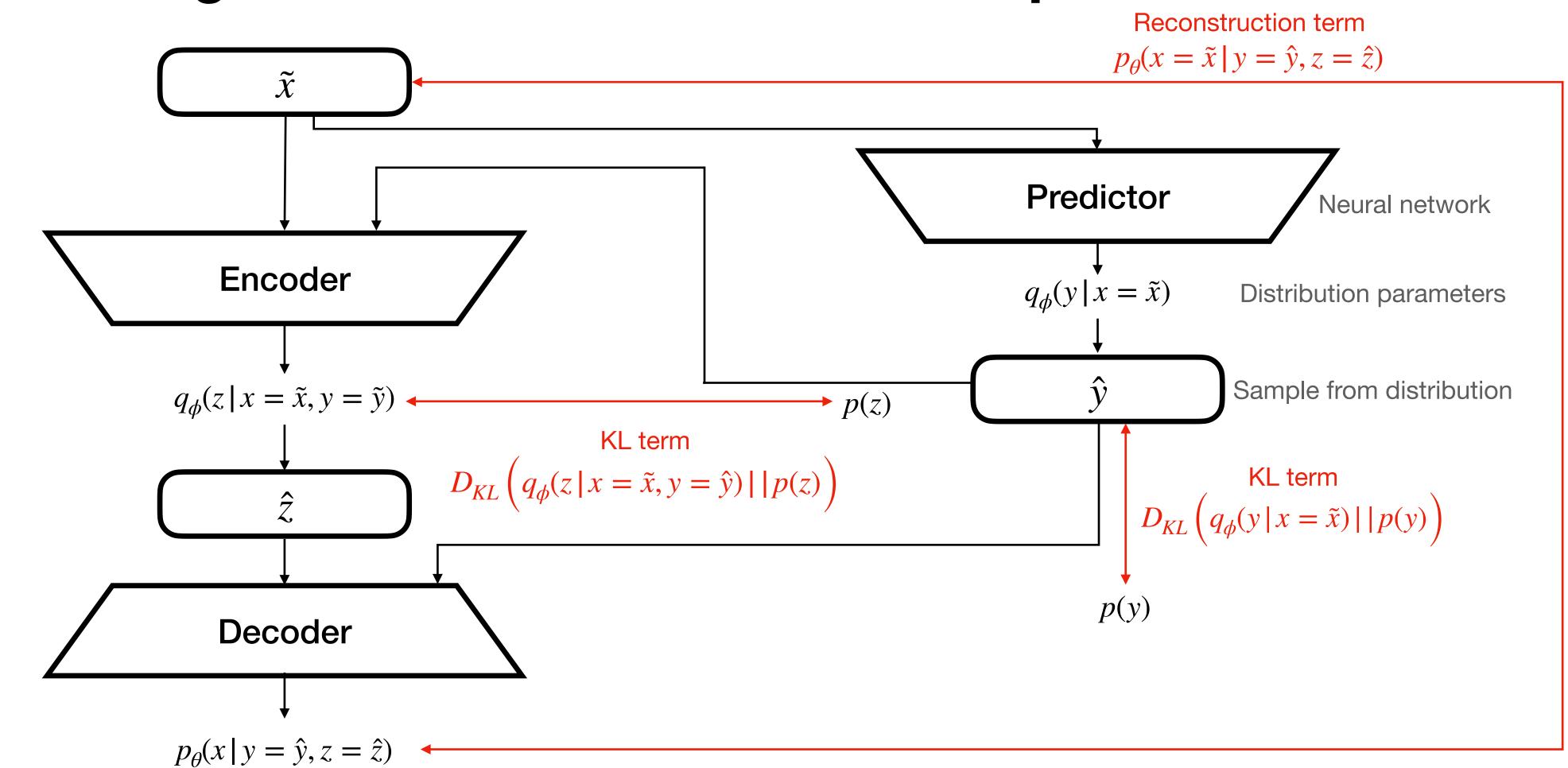
$$\mathcal{J} = \sum_{x,y \sim p_l} \mathcal{L}(x,y) + \sum_{x \sim p_u} U(x) + \beta \sum_{x,y \sim p_l} ||y - \mathbb{E}_{\hat{y} \sim q_{\phi}(y|x)} \hat{y}||^2$$

- $\mathscr{J}$  is overall training objective (to be minimised)
- $p_l$  for labelled data,  $p_u$  for unlabelled data
- Last term trains predictor to predict observed properties from labelled data
- $\beta$  is hyperparameter, controls tradeoff between generative and discriminative learning

#### What does training look like for labelled data points?



What does training look like for unlabelled data points?



Input data

Neural network

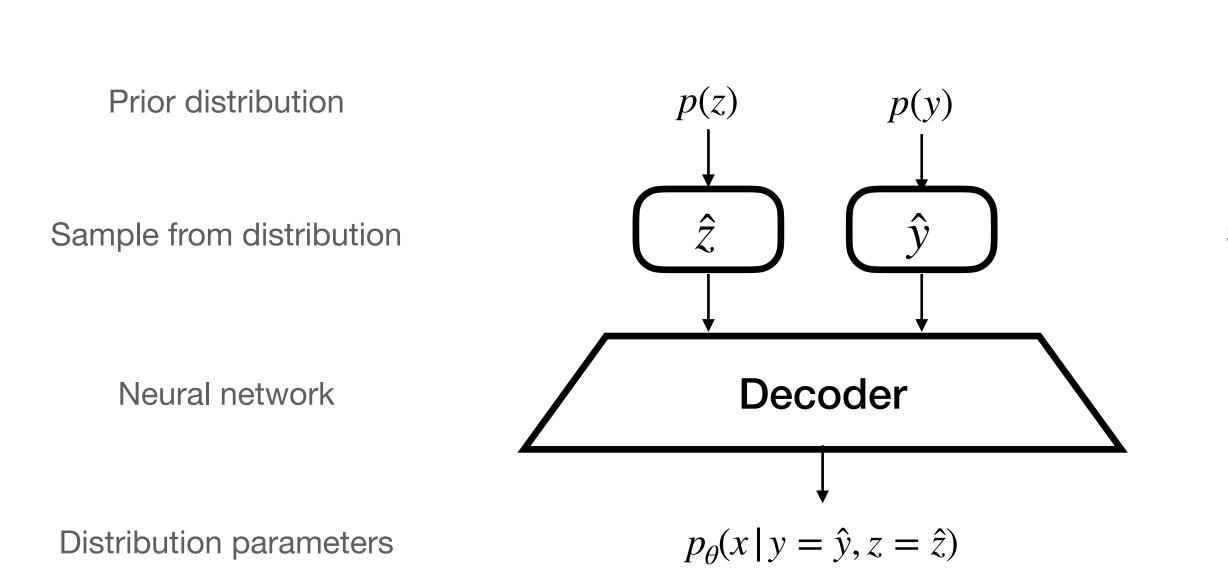
Distribution parameters

Sample from distribution

Neural network

Distribution parameters

#### What does unconditional generation look like?

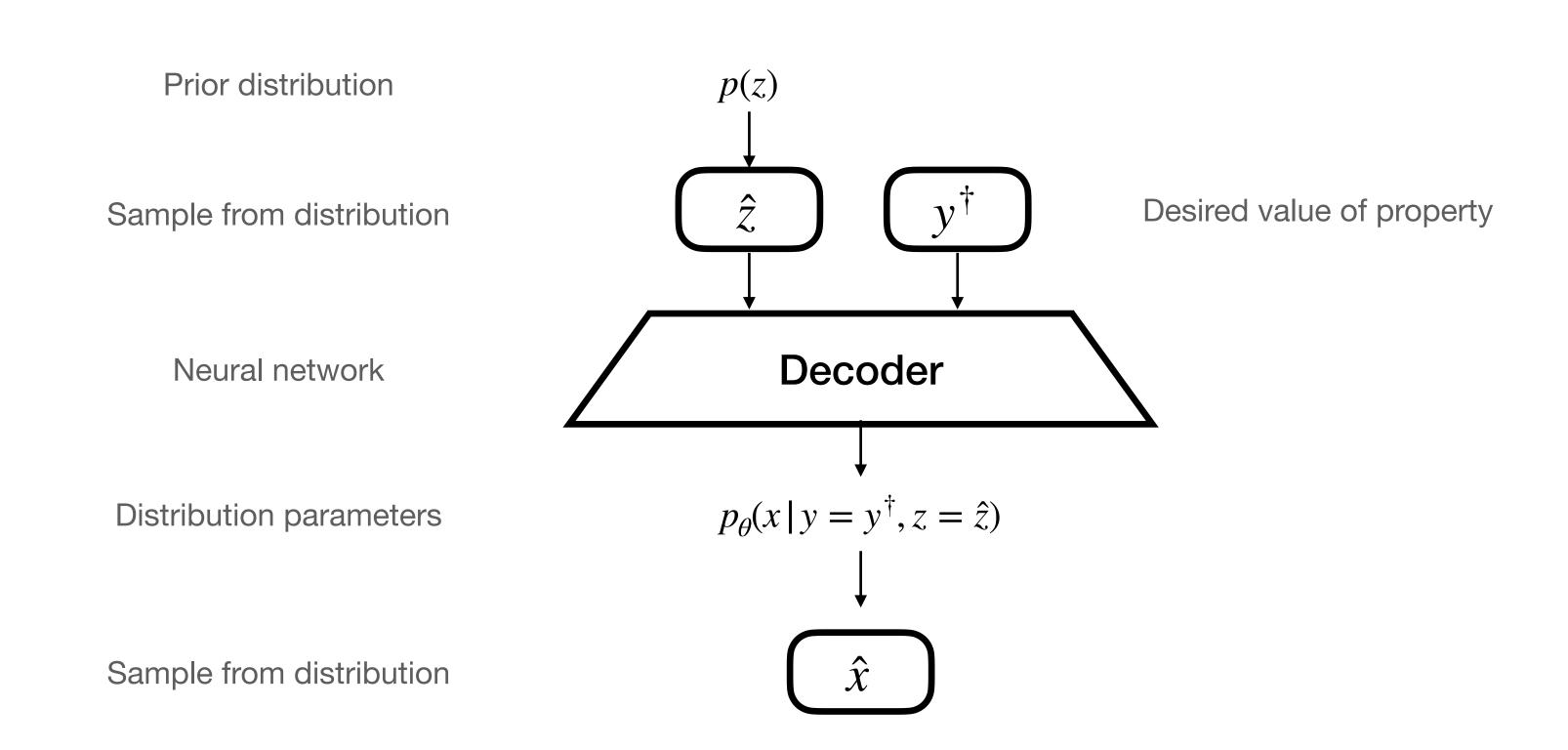


Prior distribution

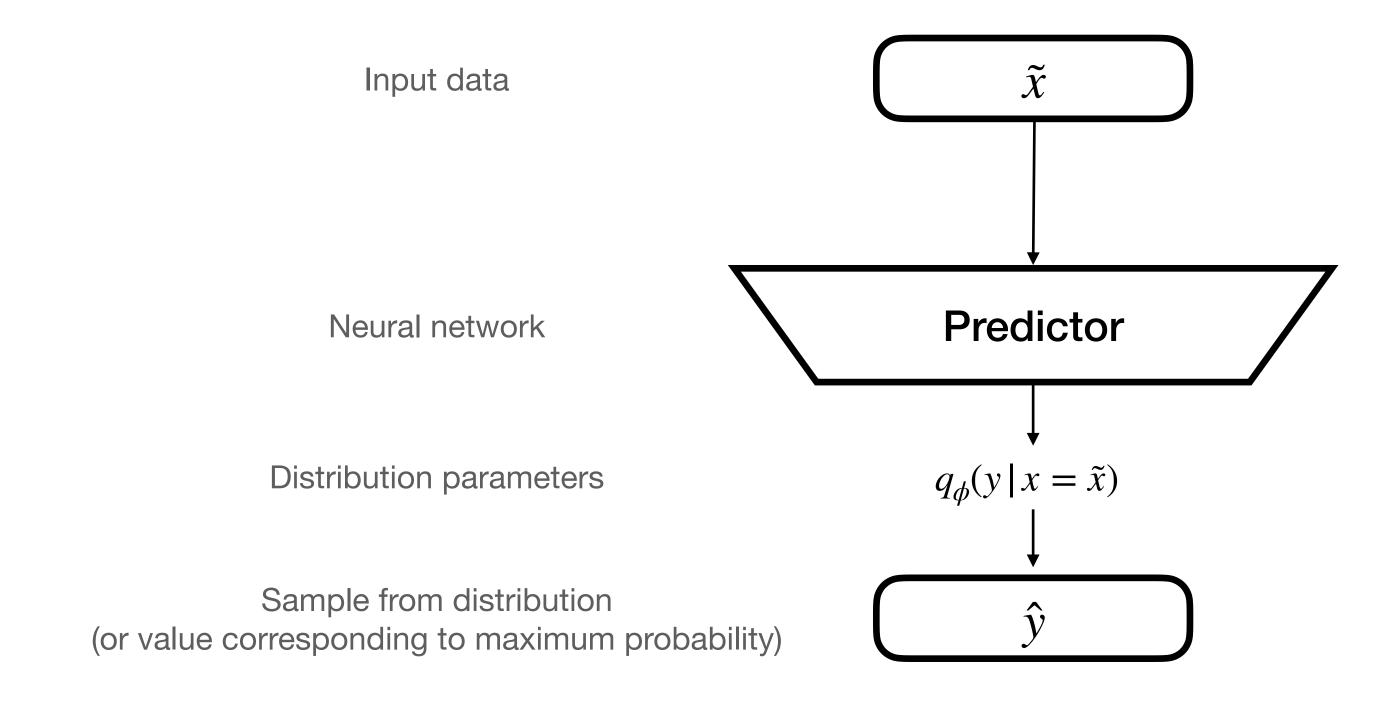
Sample from distribution

Sample from distribution

#### What does conditional generation look like?



What does property prediction look like?



## Recap

#### Recap

- Generative models model data generating distribution p(x)
- For (semi-) supervised learning they model p(x, y)
- VAEs are a type of generative model
- Conditional VAEs extend VAEs to a supervised setting
- Semi-supervised VAEs extend VAEs and conditional VAEs to a semisupervised setting

#### References

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Slide on "Taxonomy of Deep Generative Models" taken from Stanford course CS231n taught in 2017